

$$V_1 = k V_0$$

$$V_2 = V_1 V_s = \frac{-d_2 k}{16(d_1 + d_2)} (1 - \cos(4\pi f_c t)) +$$

$$+ \frac{d_2 k}{32(d_1 + d_2)} \left(\sin\left(\left(4f_c + \frac{V}{L}\right)\pi t\right) - \sin\left(\left(4f_c - \frac{V}{L}\right)\pi t\right) + 2\sin\left(\pi \frac{V}{L} t\right) \right)$$

since $f_c > \text{LPF}$ phase shift $f_c = 5 \text{ kHz}$
 $f = \frac{2V}{L} = 4 \cdot 10^3 \text{ Hz}$

$$V_3 = \frac{-d_2 k}{16(d_1 + d_2)} \left(1 + \sin\left(\pi \frac{V}{L} t\right) \right)$$

if $f_c > 5$ is satisfied then the filter will pass the signal $\textcircled{2}$
 if $f_c < 5$ is not satisfied then the filter will not pass the signal

$$f_c > 5 \left(\frac{V}{2L}\right)$$

$$V < 4 \Rightarrow V_{\max} = 4 \text{ m/s}$$